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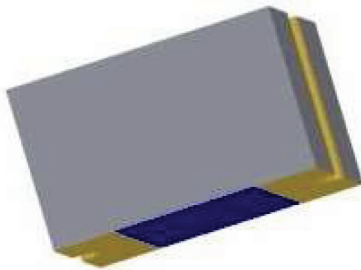
# DATASHEET

## Micro Vibration Sensor MVS0608.02

Revision 2.4

Supersedes data of 2010 Dez. 07

2011 Mar. 22



## FEATURES

- Omnidirectional vibration sensor
- Wide supply voltage range: 1.80 V to 15 V
- Low operating current  
(e.g.  $I_{cc}$  max. 0.2  $\mu$ A at  $V_{cc}$  2V and R 10Meg)  
(e.g.  $I_{cc}$  max. 2.0  $\mu$ A at  $V_{cc}$  2V and R 1Meg)
- Noiseless
- $R_{On} < 100 \Omega$
- Protected against environmental stress
- Automated SMT-mounting
- RoHS compliant, lead free
- Specified from -20 °C to +70 °C
- Size 2.85 mm x 2.45 mm x 1.7 mm
- Reacting point: approx. 50 mg

## APPLICATIONS

- Motion detection
- System wake up – low power

## MATERIAL

Package: PCB laminate material  
Inner contact material: Gold plated  
Ball: Stainless steel, gold plated

## DESCRIPTION

The micro vibration sensor is used for the detection of slight movements and vibrations by means of a mobile micro sphere. The ball bridges two contacts reducing the resistance between the two external connection pads from several mega ohms ( $> 30 \text{ MOhm}$ ) to below 100 Ohms. The sensor is fully passive, requires no signal conditioning, and operates with currents as low as 0.2  $\mu$ A.

With the aid of tool-specific evaluation electronics, the micro vibration sensor controls the operation of movement-sensitive devices. The micro vibration sensor is utilised for converting many systems to environmentally friendly devices by implementing wake-up and powerdown logic to conserve battery power and bringing energy consumption to a minimum, pushing the availability of green technology and green electronics into new areas of design and application.

The sensor is typically used for applications such as bike computers, remote controls, electronic lock systems, RFID transponders, GPS tracking systems, wireless sensor networks, illuminated dog's collars, access control systems, data loggers, bicycle lights, that are only switched on when in motion.

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## 1. Operating Conditions

| PARAMETER                     | SYMBOL    | MIN   | MAX  | UNIT |
|-------------------------------|-----------|-------|------|------|
| Supply voltage                | $V_{CC}$  | +1.80 | +15  | Vdc  |
| Current                       | $I_{CC}$  |       | 2    | mA   |
| R Open                        | $R_O$     | -     | > 30 | MOhm |
| R Closed                      | $R_C$     | < 100 | -    | Ohm  |
| Operating ambient temperature | $T_{amb}$ | -20   | +70  | °C   |

\* Current consumption is determined by the resistance of the application circuit and the supply voltage. The sensor is fully passive, requires no signal conditioning, and operates with currents as low as 0.2  $\mu$ A.

(e.g. max.  $I_{CC}$  0.2 $\mu$ A at  $V_{CC}$  2V and R 10Meg)

(e.g. max.  $I_{CC}$  2.0 $\mu$ A at  $V_{CC}$  2V and R 1Meg)

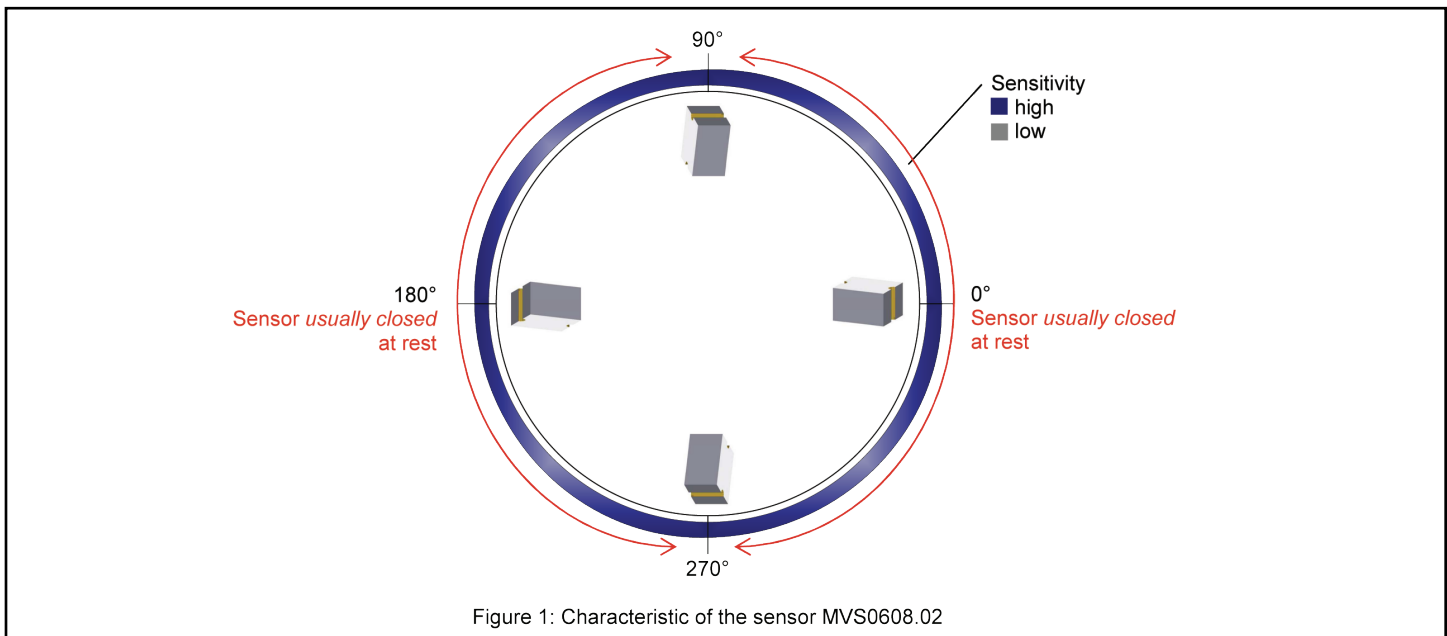
## 2. Soldering Process

Reflow Soldering Process 260°C, 10 sec

## 3. Functionality

A mobile, gilded micro sphere is located inside the hollow space of the sensor. When moving, the micro sphere bridges two gilded contacts by switching over from a high resistive to a low resistive state. When the Sensor is at rest, it is not necessarily closed. Only in 70% - 99% of time the sensor will be closed when at rest.

The figure shows the typical characteristics of the sensor in excitation and rest.



## 4. Qualification

### High temperature and high humidity storage

Test time: 48h  
Test temperature: 50°C  
Humidity: 90%  
without condensation  
no evidence of internal corrosion after the test.

### High humidity storage

Test time: 96 h  
Test temperature: 40°C  
Test humidity: 95%  
no evidence of internal corrosion after the test.  
no shape distortion

### Temperature cycle storage

Test cycle: 8 cycles, T1 = 65°C for 6h, T2 = -20°C for 6h,  
temperature change rate = 3K/min  
no evidence of internal corrosion after the test.  
no shape distortion

### Non Operation Half Sine Shock

Test cycle: Acceleration 25g at 6msec pulse width  
1000 cycles pos. 1000cycles neg.; 1Shock/s; 3 axis: X, Y, Z

### Non Operational Vibration Test

Test cycle: Sinus 10 ... 300Hz; Elongation 0.25mm / 0.25g; 5 cycles; 1 axis  
Frequency area A: 10 – 22.28Hz, amplitude in A: 0.25 mm  
Frequency area B: 22.28 - 300Hz, acceleration in B: 0.25g  
Sweep speed: 1 Octave/min, Cycles: 10  
Time per Sweep: 4.9 min

### Non Operational Vibration Test

Test cycle: Sinus 10 ... 500Hz; Elongation 3.0mm / 1.5g; 5 cycles; 1 axis  
Frequency area A: 10 – 15.76Hz, Amplitude in A: 3.0mm  
Frequency area B: 15.76 - 500Hz, Acceleration in B: 1.5 g  
Sweep speed: 1 Octave/min, Number of sweeps: 10  
Time per Sweep: 5.62 min

## 5. Package mechanical data

### 5.1 Package outline

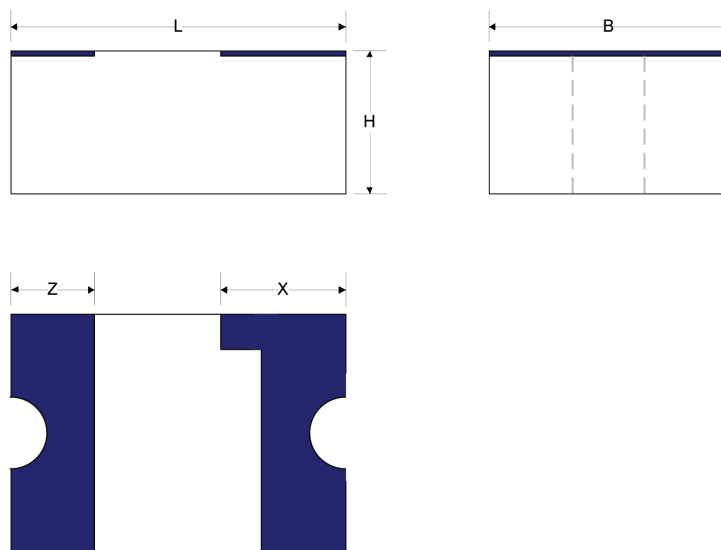


Figure 2: Package outline (drawing not to scale)

#### DIMENSIONS (mm)

| Symbol | Value (mm) | Tolerance |
|--------|------------|-----------|
| L      | 2.850      | ±0.125    |
| H      | 1.700      | ±0.125    |
| B      | 2.450      | ±0.125    |
| Z      | 0.675      | ±0.125    |
| X*     | 1.055      | ±0.125    |

\*Depending on the sensor orientation in the SMD belt or in the tray, the flag can be on the right or left side.

### 5.2 Footprint

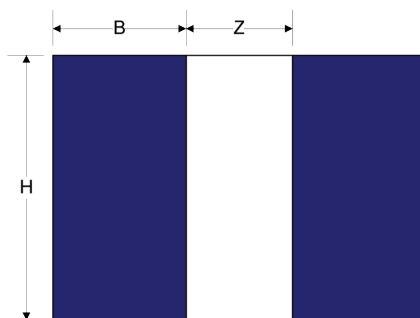


Figure 3: Recommended footprint (drawing not to scale)

#### DIMENSIONS (mm)

| Symbol | Value (mm) |
|--------|------------|
| H      | 2.80       |
| B      | 1.40       |
| Z      | 1.00       |

## 6. Ordering information

### 6.1 Tape and reel (standard-packing)

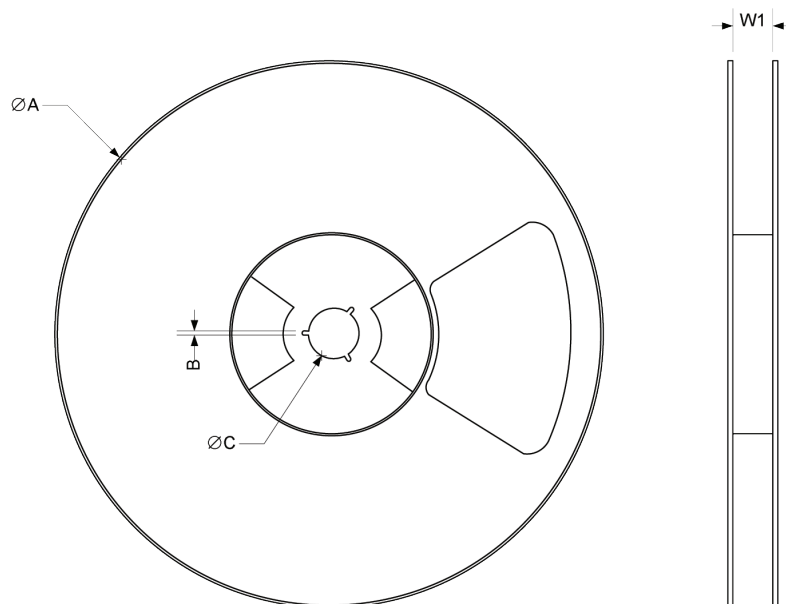


Figure 4: Reel information (drawing not to scale)

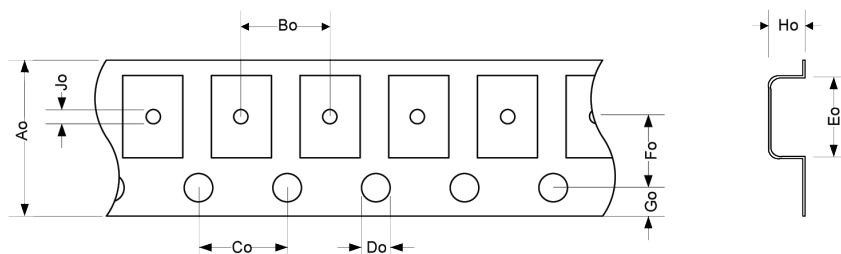


Figure 5: Tape information (drawing not to scale)

#### DIMENSIONS (mm)

| Symbol | Min    | Max    |
|--------|--------|--------|
| ØA     | 179.50 | 180.50 |
| B      | 2.00   | 2.50   |
| ØC     | 8.40   | 9.90   |
| W1     | 8.40   | 9.90   |
| Ao     | 7.70   | 8.30   |
| Bo     | 3.90   | 4.10   |
| Co     | 3.90   | 4.10   |
| Do     | 1.40   | 1.60   |
| Jo     | 0.80   | 1.20   |
| Go     | 1.74   | 1.76   |
| Fo     | 3.45   | 3.55   |
| Eo     | 3.50   | 3.70   |
| Ho     | 1.90   | 2.10   |

## 6.2 Tray (special-packing)

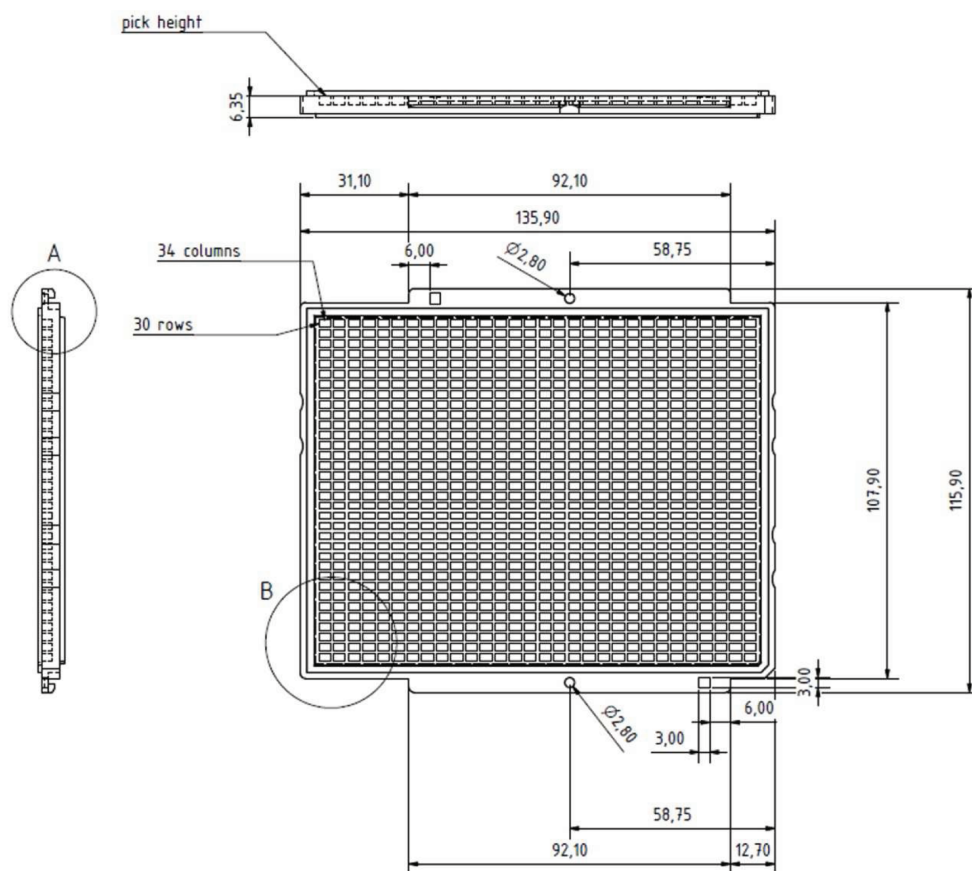


Figure 6: Tray (drawing not to scale)

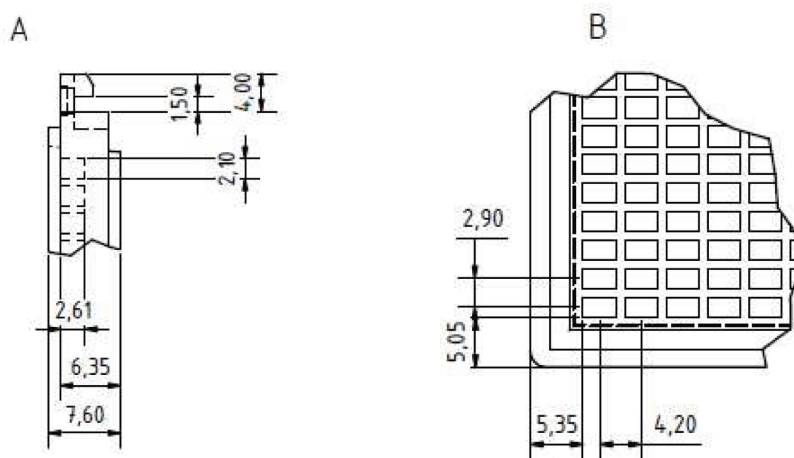


Figure 7: Detail view (drawing not to scale)